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Quantification of the impact of spillback modeling in assessing network reliability

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ABSTRACT
The quality of a road network should be that it offers reliable connections between origins and destinations under all prevailing conditions. Travel time and connectivity reliability are most important quality items. This is why robustness of a network is as main aim for road network managers these days, is becoming an important study area for transportation scientists now. This paper studies one specific aspect of robustness: the consequences of the blocking of a link in a road network using a traffic simulator. In dynamic traffic simulation program, sequentially links are blocked from a regional size network used as case study. The simulation program determines the network performance, both with a fixed route choice and an adaptive route choice. A special feature in the new simulator proposed here is that the representation of spillback can be switched on and off; thus, effects of spillback can be examined explicitly. Road network robustness and characteristics of vulnerable links are evaluated for both spillback and non-spillback cases. We conclude three things. First, the correlation of the vulnerability of links between simulations with spillback and without spillback is low, implying that any study to identify vulnerable links should include spillback. Second, network performance drops most if a freeway link is blocked. Only if simulated with spillback, freeway junction links also have a big impact. Finally, computations show that route adjustments are more effective if no spillback is simulated.
INTRODUCTION

The reliability of road networks is valued by both travelers and network authorities (1, 2). Bates found that one minute reduction of standard deviation of travel time and two minutes of actual travel time are equally valued (3). Bogers and Van Zuylen (4) showed that drivers avoid routes that are on the average the quickest but have a probability if exceptional high travel times. Robustness of networks is the ability of a network to cope with variations in demand or network capacity without much influence of travel times and is as such a cornerstone for travel time to reliability. The mentioned variations can be caused by normal daily fluctuations in demand and supply as empirically shown by Tu et al. (5). Another cause for this variation is the blocking of a link by an incident of road maintenance. This is not part of the normal daily fluctuations and reduces the capacity.

This paper analyzes this reduction of performance of a network caused by an incident. Different research projects assessing road network robustness use different traffic simulation models. The models differ in the dynamics of traffic flow and congestion. Due to the complexity of the network modeling, sometimes spillback, i.e. congestion propagation to a more upstream link, is not modeled. This contribution compares link network robustness for scenarios with and without spillback in order to assess the impact of proper spillback modeling on network performance. This is done by a dynamic model. This study makes a distinction for cases in which road users adapt their route choice to the new situation with a blocked link and congestion and a situation in which they do not. It is also investigated for the blocking of which links the network performance is particularly sensitive.

The method we use is as follows. We sequentially block all links, one at a time, and compare the results in network performance. The robustness is inverse proportional to the number of links that reduce the network performance in a considerable way. The robustness of the network depends on the internal structure and the flows in the network.

Different models, with and without spillback, predict different traffic states. This paper discusses the quantification of these differences. The main aim is to compare the conclusions from two models and conclusions about robustness and properties of important links: do they differ and how much. The next question is if robustness studies using network models without spillback have any practical value. It is found that the robustness assessment differs much for the two approaches. Therefore spillback should be well modeled in robustness studies.

The paper is set up as follows. First, it investigates which approaches to robustness are used. We will then formulate the mathematics of one approach. This mathematical framework can be applied to simulation studies. The section “traffic flow modeling” describes the differences between these studies. We will compare the simulation techniques in a case study that is described in the next section. In the last two sections present the results and the conclusions.

STATE OF THE ART

A considerable part of the delays, about 25% at least, is caused by incidents (6). In this article, we discuss these delays in detail. The robustness against link failure is usually approached in one of the following two ways:

The first one, used in (7, 8), is an analytical, game theoretical approach in a static assignment. An “evil entity” wants to destroy a network and is given the possibility to destroy a limited number of links, whereas the user wants to minimize the risk. The road users choose their routes in order to get a short travel time. Usually, it is assumed that drivers take the route such that they can not unilaterally change their route and get a higher utility, usually based on travel time (9). Those links that reduce the network performance most if they are blocked are
called vulnerable. The lower the effect of the dropout of links, the more robust a network is considered to be. In this approach, results are based on an analytical approach and a mathematical framework is set; in both articles, a simple network is used as test case. The same approach is also used in (10), but here, the travel times also depend on the flow on the links.

The other approach found in literature, is the identification of vulnerable links in a real-size network, for instance using simulation. In (11), properties of vulnerable links are presented based on a simulation study. A method to find vulnerable links quickly in large networks is proposed in (12), but in an aim to reduce computation time, the traffic dynamics are not captured correctly. In (13) a method is presented to select the most vulnerable links in different stages. The first stage selects potentially vulnerable links and links that do not need to be reconsidered for being very vulnerable. This first selection is based on link flow properties in the every day situation.

Our research aims at problems in a real-world network. This study uses the mathematical concepts of the analytical studies, but we use a dynamic traffic assignment. Thus, also spillback effects in a non-equilibrium situation can be studied.

** MATHEMATICAL APPROACH **

In the remainder of this section, we will use the following notation:

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Meaning</th>
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<tbody>
<tr>
<td>B</td>
<td>Blocked link</td>
</tr>
<tr>
<td>G</td>
<td>The network</td>
</tr>
<tr>
<td>G_b</td>
<td>The network with link b blocked</td>
</tr>
<tr>
<td>π</td>
<td>Path</td>
</tr>
<tr>
<td>Ss</td>
<td>Spillback simulation: is in the simulation spillback simulated or not</td>
</tr>
<tr>
<td>π₀*(G)</td>
<td>Set of optimal static paths in network G</td>
</tr>
<tr>
<td>π*(G)</td>
<td>Equilibrium paths in network G</td>
</tr>
<tr>
<td>A</td>
<td>Number of travelers arrived at the end of the simulation</td>
</tr>
<tr>
<td>A(π,G,ss)</td>
<td>Number of travelers arrived at their destination at the end of the simulation given route choice π, network G and whether spillback is simulated or not</td>
</tr>
<tr>
<td>A(π₀*(G),G_b,ss)</td>
<td>Number of travelers arrived at their destination at the end of the simulation if link b is blocked and the route choice is based on an undisturbed, free flowing network</td>
</tr>
<tr>
<td>A(π*(G),G_b,ss)</td>
<td>Number of travelers arrived at their destination at the end of the simulation if link b is blocked and the route choice is based on the actual traffic situation</td>
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There are two (groups of) actors in the situation at hand: on the one hand the travelers all wanting the best path through the network and on the other hand an “evil entity” wanting to harm the performance most by blocking one link. The network robustness studied here can be easily related to the performance of the evil entity. If a link is blocked, the evil entity wants the network performance to reduce a lot. Road users, on the other hand, all aim for a short travel time independent of the link blocking. The collective result of the trips of all travelers is a measure for the network performance. As road users want to optimize their individual trip
under for all circumstances, the aim for the collective of road users is a robust network, although in general the individual optimal route choice does not lead to a collective optimum. The situation is studied in two ways here. The first way is that the road users choose the initially fastest routes and do not deviate from it, even if their route is congested or blocked. In the second way, a road is blocked and road users will adapt their routes according to the new situation.

**Static, predetermined routes**

In this scenario, the best routes through the network are determined first. Routes are chosen according to a user based optimum. Everyone takes the route that is fastest in his perception. These routes are referred to as $\pi_0^*$ ($G$), in which $G$ is the network these routes are based on. For reasons of simplicity, routes are in this case based on an undisturbed network and free flow travel times which is indicated with the subscript 0. The travel times are subject to personal valuation and perception, even if they are based on free flow conditions. Therefore, in the simulation program, a number of sets of link travel time perceptions are drawn. The link travel time is drawn from a normal distribution with the calculated travel time as mean and a standard deviation of 10%. This value comes from the qualitative calibration of the network we will use as case study (see below). Each set of link travel time drawings determines a set of routes from each point to each destination. A large number of drawings can be considered representative for the whole population and so routes are assigned via a probit procedure.

For the trips from every node in the network to each destination a route choice is now made. Then, one link is blocked and the network $G$ changes into $G_b$. For every link blocked, a separate simulation is run. For the evaluation of the performance of a network an indicator should be used. We want this performance indicator to be lower if people need to take a detour, come later or do not arrive at their destination at all. We opted for the total number of travelers that arrive at their destination in the simulation time as performance indicator, $A$. We preferred this over average travel time as measure. That would need extra care in interpretation and calculation as it needs to be decided for which number of travelers the average is calculated and comparisons would be more complicated. It also differs from the total time spent in the network as in our performance measure, a few cars that are blocked for the whole simulation period, do not influence the network performance much. This resembles better the reality as in reality, the cars might be able to reverse or turn around.

The network flows and therefore also the network performance $A$ can be different for the scenario in which spillback is modeled and the scenario in which no spillback is modeled, so it depends also on the simulation of spillback, $ss$.

The performance of the network in this scenario can now mathematically be expressed as:

$$A(\pi_0^*(G), G_b, ss).$$

The most vulnerable link $b^*$ is the link for which the network performance is lowest if it is blocked:

$$b^* = \underset{b}{\arg\min} \left( A(\pi_0^*(G), G_b, ss) \right).$$

**Dynamically adapted routes**

Here, the simulation starts with blocking link b. The travellers respond to that action by changing their routes and therefore, their actions are different for every different link blocked. The road users adapt their behaviour to the newly envisaged situation in the blocked network, and will also change their routes during the simulated time due to congestion. In this case, the
routes are based on the actual traffic situation with a blocked link. People will choose the route that is in their view the fastest at the moment of choice, at the moment, \( \pi^*(G_b) \). No iteration is applied to account for the congestion in the coming time period. User equilibrium is not likely to occur in a non-recurrent situation with an incident. The assignment is, similar to the other scenario, done by a probit assignment. The routes are now updated every time period of fifteen minutes due to congestion. In practice, this is for example possible by regular in-car information of the speeds.

Link travel time is computed from link distance and average speed on the link, which, in turn, is the calculated flow divided by density. Travelers choose a route to their destination that takes the shortest time in their view. In this scenario, the same probit procedure is applied for the route choices. The error in travel time perception is still normally distributed with a standard deviation of 10%. Now, however, at the end of a period, this assignment is redone with updated speeds. Half of the travelers will be assigned to a new route; the other half will choose the old route for the coming period. If the fraction of people that take a different route is too small, the route choice effect cannot be seen. On the other hand, a too large share is unrealistic (1).

As network flows will differ for scenarios with and without spillback, the network performance can also differ dependent on the simulation of spillback. For this scenario, the network performance function that needs to be evaluated is

\[
A\left(\pi^*(G_b), G_b, ss\right).
\]

This function is calculated for each choice of blocked link \( b \), so that the most vulnerable link \( b^* \) can be found:

\[
b^* = \text{argmin}_{b} \left( A\left(\pi^*(G_b), G_b, ss\right) \right).
\]

In terms of a mathematical game, this link \( b^* \) would be the Stackelberg optimum for an evil entity to block if he was given the opportunity to block one link.

**TRAFFIC FLOW MODELLING**

Analysis to road network robustness can be done with two types of simulations. Both microscopic simulations, in which vehicles are individually simulated, and macroscopic simulations are used.

Simulation studies that cover a larger area often use macroscopic models to reduce computation time. With these models, it is an issue to implement the congestion flow crossing a link border in a correct way. Often, queuing models are used to describe queues. In vertical queuing models, traffic jams do not occupy any space. What matters for the traffic flow, is that flow at the upstream link is not influenced by the queues on the (downstream) link. In reality, the queue will grow more upstream than the end of a link. This can be captured by a horizontal queuing model. In this model, the head of the queue is fixed at the bottleneck and the queue can only dissolve from the tail. Often, a fixed space per car is assumed. The queue dynamics of this model are plotted in Figure 1a. In the upper figure, the space-time diagram of the queue is plotted. The queuing area is shaded. In the lower figure, the number of cars in the queue is plotted.

In reality, the queue will, possibly dependent on traffic conditions, dissolve from the head, while the tail of the queue still moves upstream, as seen in Figure 1b and c. Figure 1b give the representation of the correct traffic behavior at the bottleneck, but without spillback: the queue remains at the links of the bottleneck. In Figure 1c, also the spillback is captured correctly: the queue grows also on the upstream link and the growing on the tail is faster as
soon as it crossed the link border. This study compares the situation without spillback (as in Figure 1b) with the situation of spillback as shown in Figure 1c.

![Figure 1](image)

Figure 1: Congestion dynamics in a space-time plane. From left to right: a) implementation of a horizontal queueing model, b) shockwave theory without spillback, c) shockwave theory with spillback

Shockwave theory is needed to describe the real traffic state (Figure 1c) behavior sufficiently accurate. We use a continuum LWR-model that we solve with a Godunov scheme (14). Second order effects (e.g. from synchronized flow to wide moving jams) have some minor influences (15) that we will neglect in the remainder of this article.

**CASE STUDY DESCRIPTION**

The best way to compare the results of the vulnerability of links in a spillback and in a non-spillback simulator is to use one simulator that can run simulations both with and without spillback. In this way, there are no differences in systematic errors. We used a simulator DSMART developed at Delft University of Technology. The working of the simulator is discussed briefly here; for more details, we refer to (16). The macroscopic simulator splits links in cells. In each cell, the density and the average speed are assumed homogeneous; these two variables determine the state of the cell. A fundamental diagram gives a relation between density and flow; we used a triangular shaped fundamental diagram (17). This fundamental diagram is used in a Godunov scheme (18): according to the density and this fundamental diagram, every cell has a certain output demand, increasing with density, and a supply ability, decreasing with density. The minimum of the demand of the upstream cell and the supply of the downstream cell is the flow from one cell to the adjacent cell:

\[ Q_{i+1} = \min \{ \text{demand}_i, \text{supply}_{i+1} \} \]  

If at junctions the combined demand of the upstream links to one downstream link is larger than the supply of the downstream link, the transmission flow from all upstream links is reduced with an equal factor (19). In this way, vehicles queue at the upstream link and so congestion propagates upstream and spillback is put in the model.
A modification of the model excludes spillback from the model. In this changed model, the supply of the most upstream cell of a link was always, independent of the congestion state, capacity. In this model, a traffic jam on the downstream link does not influence the traffic state on the upstream link.

As a case study, we use the network of freeways and the main roads of the underlying road network around the Dutch city of Rotterdam (around 600,000 inhabitants, see also Figure 2).

![Map of the city of Rotterdam](image)

**Figure 2 Map of the city of Rotterdam**

468 links are modeled. The network model and the dynamic OD matrices are calibrated qualitatively on a morning peak period. Our simulation covered a morning peak from 6.30 to 9.30 am.

The incidents are modeled as follows. During the whole simulation, the capacity of a link is reduced. The new capacity of the blocked road is expressed mathematically as:

$$
C_{\text{blocked}} = C_{\text{old}} \max \left\{ \frac{nrlanes - 2}{nrlanes}, 0 \right\}
$$

in which C stands for the capacity of the links. This means that at most two lanes will be blocked.

**RESULTS**

Four different scenarios are compared:
- no spillback, static route choice;
- no spillback, dynamic route choice;
- spillback, static route choice;
- spillback, dynamic route choice.

In this section, we compare the results of these simulations, starting with some general findings. Then we analyze the advantage of path updates in cases with and without spillback. In the next subsection, we compare the network robustness in cases with and without spillback. In the last two subsections, we assess the impact of the blockings of the individual links. First, we see that the blocking of a freeway link has the most impact on the network performance. In the last subsection, it is set out why a network performance reduction computed without spillback does not give information on the network performance reduction with spillback simulated.
General findings
Comparing the results of two situations only differing in spillback (so the same link blocked, same settings for route choice), in the simulation without spillback, more travelers arrive at their destination in the simulation time. At the end of this section, we will discuss this result, more extensively. Comparing the results of two situations only differing in path update (so the same link blocked and the same spillback model used), in the simulation with path update, more people arrive (in almost all cases). Both results are obvious and according to the expectations. More relevant and interesting results can be found in the next subsections.

Performance increase due to route updates
If the results are analyzed more closely, there appear to be interesting differences between several scenarios. From the results we computed the relative advantage of updating the paths:

$$adv(b, ss) = \frac{A(\pi^*(G_b), G_b, ss) - A(\pi_0^*(G), G_b, ss)}{A(\pi_0^*(G), G_b, ss)}.$$  

(7)

For both cases of spillback simulation, we simulate the network with each of the 468 links blocked (sequentially). Per scenario, we then get 468 values for the network performance, one for every blocked link. These values were ordered and plotted, as cumulative distribution, in Figure 3. It shows that the advantage of updating paths is computed to be much bigger if spillback is not simulated.

The possibilities to take alternative routes get better if congestion spillback is not present in the simulation. So, the advantage of the path update is bigger in the case with spillback than in the case without.

Network robustness with and without spillback simulation
The assessment of the robustness of the network is done by evaluating the impact of blocking single links. In Figure 4, the cumulative distribution function of the performance indicator relative to the maximum number of each scenario is plotted. Note that this plot is not a distribution function of the absolute network performance.
From this figure, we can see what the (relative) performance of the network is if a randomly chosen link is blocked. This can be related to robustness in the following way. We will take a threshold value for the network performance decrease and find the probability that the decrease is more, given that one randomly chosen link is blocked. If that probability is small, the robustness is high.

This threshold value should be a typical value for the performance reduction if link is blocked. This depends for instance on the network size and chosen performance. In the case at hand, a good value is 4% drop of performance compared to the maximum performance obtained in the scenario (generally no link blocked, except a possible Braess’s paradox (20)). This is the 0.96 mark at the x-axis. The according values at the y-axis indicate the chance that if a randomly chosen link is blocked, the decrease of the performance compared to the maximum performance is more than 4%. In Table 2 below, these values that can be read from the graph are stated.

<table>
<thead>
<tr>
<th></th>
<th>Spillback</th>
<th>No spillback modeled</th>
</tr>
</thead>
<tbody>
<tr>
<td>No path update</td>
<td>41 %</td>
<td>13 %</td>
</tr>
<tr>
<td>Path update</td>
<td>42 %</td>
<td>20 %</td>
</tr>
</tbody>
</table>

From this table, we can see that without spillback modeled, a big error is made. If congestion spillback is not taken into account, the performance reduction caused by the blocking of one randomly chosen link would in (at most) 20% of the cases exceed 4%. This percentage of vulnerable links will increase sharply if spillback is modeled: it doubles from at most 20% to more than 40%. Keep in mind that the indicated performance drop is the drop in a certain scenario. So, the difference in vulnerability is not a consequence of the natural lower
performance of a simulation in which spillback is included. Also, the natural higher performance of a network with path update does not influence these numbers.

**Blocking of freeway links causes problems**

For each of the links blocked, the network performance can be calculated. The impact of the blocking is dependent on the link. This impact is shown in Figure 5a. A red link means that the network performance decreases heavily if that link is blocked, while the blocking of a green link has a low impact on the network performance. The figure is the mean impact of the four scenarios.

From the data, we see that heavily used freeways are, independent of the scenario, the most vulnerable. If one of these links is blocked, the network performance drops most. For one type of link, the difference in impact for the scenarios with spillback and without spillback is bigger than for other types. These are the connecting links in freeway junctions. If they are blocked in a non-spillback scenario, they turn out not to be that important. However, if one of these connecting links is blocked in a spillback scenario, the network performance reduced considerably more. Figure 5b shows the difference in calculated impact of link blocking. The shown freeway junction is the junction in the oval in Figure 5a. The links for which the impact factor differs the most, are colored red.

![Figure 5 a) the impact of the blocking of a link b) the difference in link impact caused by spillback modeling](image)

**No correlation in robustness value of link computed with and without spillback**

Finally, we compare the impacts of the blocking of the distinct links on the network performance for both the spillback and non-spillback cases. This is plotted in Figure 6. We carry out a correlation analysis to see how well the computed impact of the blocking of a link can foretell the impact of the blocking of the link if spillback is included.
Figure 6 Comparison of network performances with and without spillback

On the x-axis of the figure is the number of arrived travelers in a case without spillback modeled indicated, the y-axis gives the number of arrived travelers in a case spillback is modeled. A marker in this area indicates the results of two simulations, with and without spillback, in the same settings for route choice (the two different settings are indicated with different markers). As indicated in the beginning of this section, it is obvious that the network performance without spillback modeled is higher than without the spillback modeled. A possible exception is that a queue has less influence if it is located further upstream due to the position in the network. Almost all results from our case study indicate that the performance in the non-spillback case is higher. Note that the axes are not equal.

Let us now consider both routing cases separately and evaluate the predictive value of the arrivals in the non-spillback case for the arrivals in the case with spillback. To check the correlation between these two values, we performed a linear regression analysis on both (paths fixed and paths update) clouds in Figure 6. We only consider each of both path update scenarios separately. The data points for the case with path update have a higher value than those without, but that is not the regression we consider here. The two regression lines are also plotted.

The resulting regression coefficients $R^2$ are 0.20 for the case with path update and 0.39 for the case without a path update. These values mean that only 20% (39% for the case without rerouting) of the variation in arrivals in the case with spillback can be explained by the variation in arrivals in the corresponding scenario without spillback. The conclusion is that simplified simulations that do not take spillback into account have very limited value for the assessment of network robustness.
CONCLUSIONS AND FURTHER RESEARCH

We simulated a morning traffic flow on a real, regional sized, network for which sequentially one of the links was blocked. The dynamic traffic simulator had the possibility to make choices about both path update and spillback. Paths could be adapted to the situation or not and, independently, spillback could be switched on and off.

The first conclusion is that in a network with a daily demand the advantage of rerouting is bigger without spillback modeled than with spillback modeled. This is because without spillback modeled, congestion on a limited number of places can be well avoided.

Secondly, we analyzed the decrease of network performance due to a drop out of a random link compared to a fully operational network. There is a difference in the estimation of performance loss relative to the performance of the fully operational network. The loss is considerably lower when the estimation is based on a simulation in which spillback is not taken into account. Consequently, robustness is overestimated if spillback is not simulated.

Thirdly, we compared the impact of the blocking of links on the network performance in scenarios with and without spillback. That showed that there is at most a very weak correlation between this impact if computed with or without spillback. Therefore, any realistic study of the impact of the blocking of a single link must include spillback.

In this paper only two route choices were considered. People could either take the route that appeared to be the fastest in free flow conditions or they would adjust the route to the actual traffic situation. In further research, the fixed routes can be made dependent on the daily congestion pattern. Also a third route choice can be added. In this case, road users, aiming for reliability, anticipate on a possible drop out of a link.

In further research also the horizontal queuing model (Figure 1a) can be examined more closely. The difference between this model and the spillback model considered in this research is mainly the location of the queue. When does the location of the queue have a big influence?

In the study only one link was blocked at a time. The consequences of blocking two or more links simultaneously are interesting. Blocking each combination of links and evaluate the network performance would be computationally too expensive. Further work could use the findings in this paper as basis and combine different valuable links that have on their own a big impact. Of course, only a spillback scenario needs to be considered.

The study showed that the robustness decreases if spillback is included, regardless of the inclusion of path updates. Further research could address the point with which measures of Traffic Management the robustness can be increased.

It would furthermore be very interesting to perform a research similar to this one but applied to an urban network. In short streets with many traffic lights spillback seems an important source of delay. Density waves and shock waves propagate over long distances throughout the network.

ACKNOWLEDGEMENTS

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